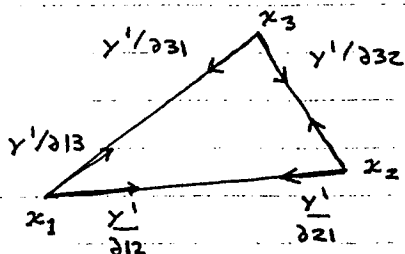


Notes: Directional Derivatives for Δ spline

2 Sept 1993



Given $\frac{\partial y}{\partial p_i}$ where p_i is e.g. units per units
such as 1 mil / $^{\circ}$ F.

We first normalize. $p_{max} - p_{min} \Rightarrow 1$ unit

So if we have 1 mil / $^{\circ}$ F and $^{\circ}$ F_{max} - $^{\circ}$ F_{min} = 500 $^{\circ}$ F

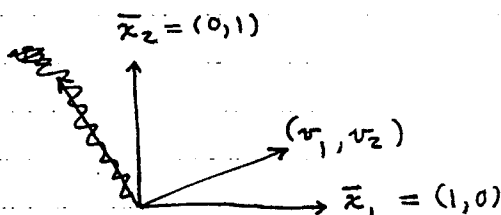
Then 1 mil / $^{\circ}$ F becomes 500 mils / 500 $^{\circ}$ F.

Thus $\frac{\partial y}{\partial \bar{x}_i} = \frac{\partial y}{\partial p_i} (p_{max} - p_{min})$.

Now we want to transform $\frac{\partial y}{\partial \bar{x}_i}$ derivatives

to the directions of line segments connecting points.

ex: \vec{v} in direction from x_1 to $x_2 = \frac{x_2 - x_1}{\sqrt{|x_2 - x_1|^2}}$
 \vec{v} is a unit vector = v_1, v_2



$$v_1^2 + v_2^2 = 1 \quad \frac{\partial y}{\partial \vec{v}} = v_1 \frac{\partial y}{\partial \bar{x}_1} + v_2 \frac{\partial y}{\partial \bar{x}_2}$$

Cubic Splines - N-Dimensions - Directional Derivatives^(cont.) 5

W. F. Cotton
2 Sept. 1993

In general we have

$$\vec{v} = (v_1, \dots, v_n) = \frac{x_2 - x_1}{\sqrt{|x_2 - x_1|^2}}$$

$$\frac{\partial y}{\partial \vec{v}} = v_1 \frac{\partial y}{\partial x_1} + \dots + v_n \frac{\partial y}{\partial x_n}$$

This gives us the derivative in the direction from x_1 to x_2 , but we want to normalize so the derivative is in terms of λ 's.

$$\begin{array}{l} \lambda=0 \text{ corresponds to } l \cdot \vec{v} \\ \lambda=1 \text{ " " " } 0 \cdot \vec{v} \end{array} \quad l = \sqrt{|x_2 - x_1|^2}$$

$$\text{Thus } \frac{\partial y}{\partial \vec{v}} = \frac{\partial y (l(1-\lambda) \vec{v})}{\partial \vec{v}}$$

$$\text{Anyhow } \frac{\partial y}{\partial \lambda} = -l \frac{\partial y}{\partial \vec{v}} \text{ since } \Delta \lambda = 1 \leftrightarrow \Delta \vec{v} = -l.$$

$$\text{Let } \vec{u} = x_2 - x_1 = (u_1, \dots, u_n) \quad x_1, x_2 \text{ defined pts}$$

$$\frac{\partial y}{\partial \vec{u}} \equiv \frac{\partial y}{\partial \vec{x}} = -u_1 \frac{\partial y}{\partial x_1} - \dots - u_n \frac{\partial y}{\partial x_n}$$