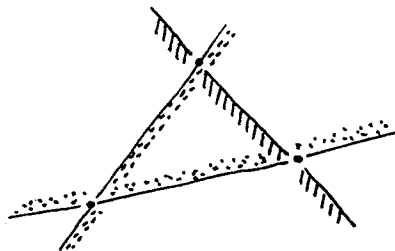


Neil E Cotter

11 May 1994

tool: To find the triangle containing a data point, test whether the data point lies on the interior side of each side of ~~the~~^a triangle. Search through all the triangles until you find the correct one.

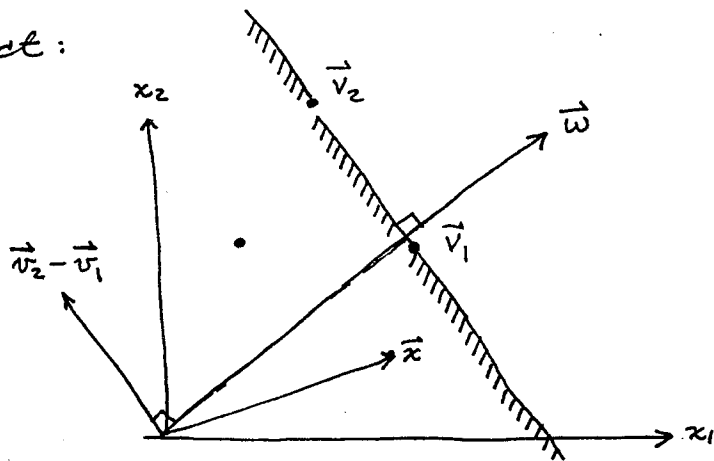
pict:



shading indicates interior sides

tool: A dot product of \vec{x} with a vector \vec{w} perpendicular to the side of a triangle determines ~~whether~~ whether \vec{x} lies on the interior or exterior of the side.

pict:



We can find \vec{w} such that $\vec{w} \perp (\vec{v}_2 - \vec{v}_1)$ where $\vec{v}_2 - \vec{v}_1$ is parallel to side defined by \vec{v}_1, \vec{v}_2 . Points \vec{x} lying on this \vec{v}_1, \vec{v}_2 side satisfy the following eq'n:

$$\vec{w} \cdot \vec{x} = c \text{ (constant)}$$

We can scale \vec{w} to make $c = 1$ to get:

\vec{x} on boundary when $\vec{w} \cdot \vec{x} = 1$ $\vec{w} \perp$ side

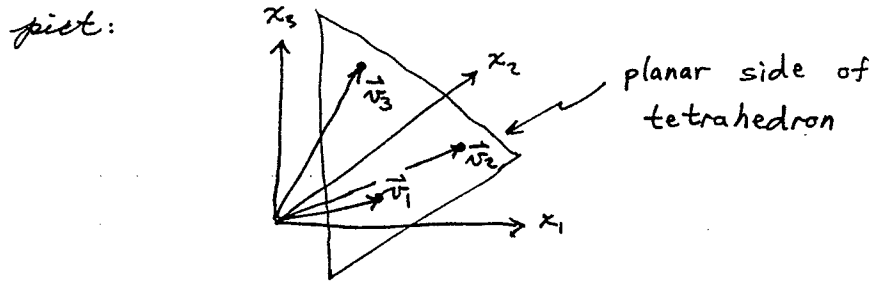
Neil E. Cotter
 1994

tool (cont): If we have $\vec{w} \cdot \vec{x} > 1$ we are on one side of the side. If we have $\vec{w} \cdot \vec{x} < 1$ we are on the other side of the side.

comment: We can find the \vec{w} 's for the sides and store them ahead of time. Then all we need to do is compute $\vec{w} \cdot \vec{x}$ when we are evaluating $f(\vec{x})$.

note: In 3 dimensions we can still use $\vec{w} \cdot \vec{x} = 1$ to define which \vec{x} are on a side of a tetrahedron (a 3-dim triangle).

tool: To find \vec{w} perpendicular to a planar side of a tetrahedron, we must find a vector \perp to $\vec{v}_1 - \vec{v}_2$ and $\vec{v}_2 - \vec{v}_3$ where $\vec{v}_1, \vec{v}_2, \vec{v}_3$ are the three data points defining the side of the tetrahedron.



Note that $\vec{v}_1 - \vec{v}_2$ and $\vec{v}_2 - \vec{v}_3$ are vectors parallel to the planar side. To find \vec{w} we solve the following equations

$$\begin{aligned} \vec{w} \cdot \vec{v}_1 &= 1 \\ \vec{w} \cdot \vec{v}_2 &= 1 \\ \vec{w} \cdot \vec{v}_3 &= 1 \end{aligned} \quad \text{or} \quad \begin{bmatrix} -\vec{v}_1 & - \\ -\vec{v}_2 & - \\ -\vec{v}_3 & - \end{bmatrix} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$$

or $V \cdot \vec{w} = \vec{1}$

Thus, $\vec{w} = V^{-1} \cdot \vec{1}$.